

# Argos3D-P230

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## Hardware User Manual

Version 2

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**Argos3D-P230** – Hardware User Manual

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Information

For further information on technology, delivery terms and conditions and prices please contact BECOM Systems [www.becom-group.com](http://www.becom-group.com)

# 1 General Information

This guide applies to the Argos3D-P230 from BECOM Systems. Follow this guide chapter by chapter to set up and understand your product. If a section of this document only applies to certain camera parts, this is indicated at the beginning of the respective section.

**The document applies to product V1.0.x**

## 1.1 Symbols Used

This guide makes use of a few symbols and conventions:



### Warning

Indicates a situation which, if not avoided, could result in minor or moderate injury and/or property damage or damage to the device.



### Caution

Indicates a situation which, if not avoided, may result in minor damage to the device, in malfunction of the device or in data loss.



### Note

Notes provide information on special issues related to the device or provide information that will make operation of the device easier.



### Procedures

**A procedure always starts with a headline**

1. The number indicates the step number of a certain procedure you are expected to follow.

Steps are numbered sequentially.



This sign ➤ indicates an expected result of your action.



### References

This symbol ⇄ indicates a cross reference to a different chapter of this manual or to an external document.

## 1.2 Certification

The product is in X-grade state.

### 1.2.1 Eye Safety

<b>Illumination: Laserdiodes</b>	<b>Wavelength</b>	850nm (typ.)	Laser classification according to EN 60825-1 pending
	<b>Output power</b>	24 W peak	



#### Caution

This device emits Laser radiation.

## 1.3 Safety instructions



#### Important

This manual is part of the device and contains information and illustrations about the correct handling of the device and must be read before installation or use. Observe the operating instructions. Non-observance of the instructions, operation which is not in accordance with use as prescribed below, wrong installation or handling can affect the safety of people and machinery.

The installation and connection must comply with the applicable national and international standards. Responsibility lies with the person installing the unit.

## 1.4 Electrical connection



#### Note

The unit must be connected by a qualified electrician.

Device of protection class III (PC III).

The electric supply must only be made via PELV circuits.

The device must only be powered by a limited energy source ( $\leq 30V$ ;  $\leq 8A$ ;  $\leq 100VA$ ).

Disconnect power before connecting the unit.

## 2 Argos3D-P230 Components

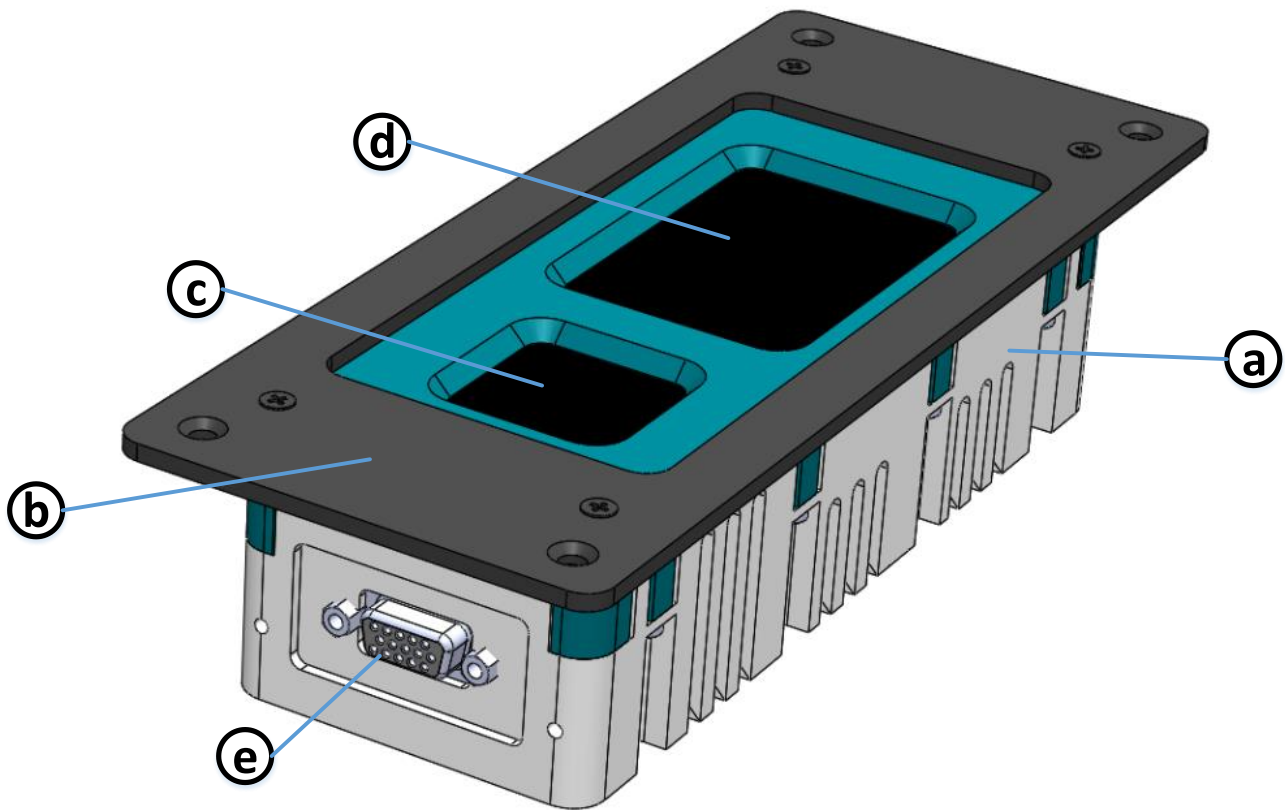


Figure 2-1 Argos3D-P230 components

- a. Case
- b. Cover plate (optional)
- c. Viewing window for 3D sensor
- d. Viewing window for illumination module
- e. IP67 compliant connector



## 3 Mechanical Description

### 3.1 Dimensions

All dimensions are in mm, tolerance +/-0,2mm.

#### 3.1.1 Top view

Top mounting hole size: M3

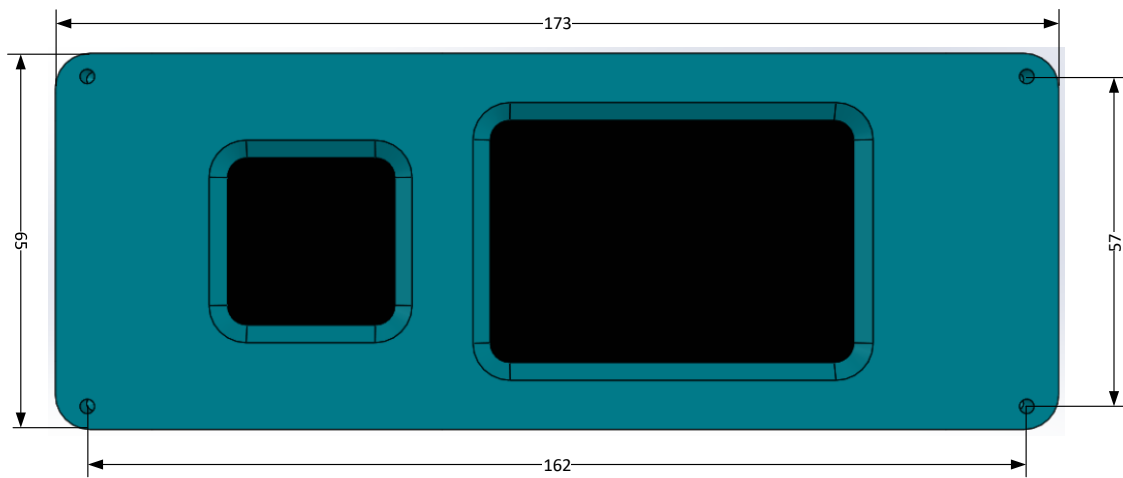


Figure 3-1: Top view dimensions without cover panel

#### 3.1.2 Front view

Front mounting hole size: M3

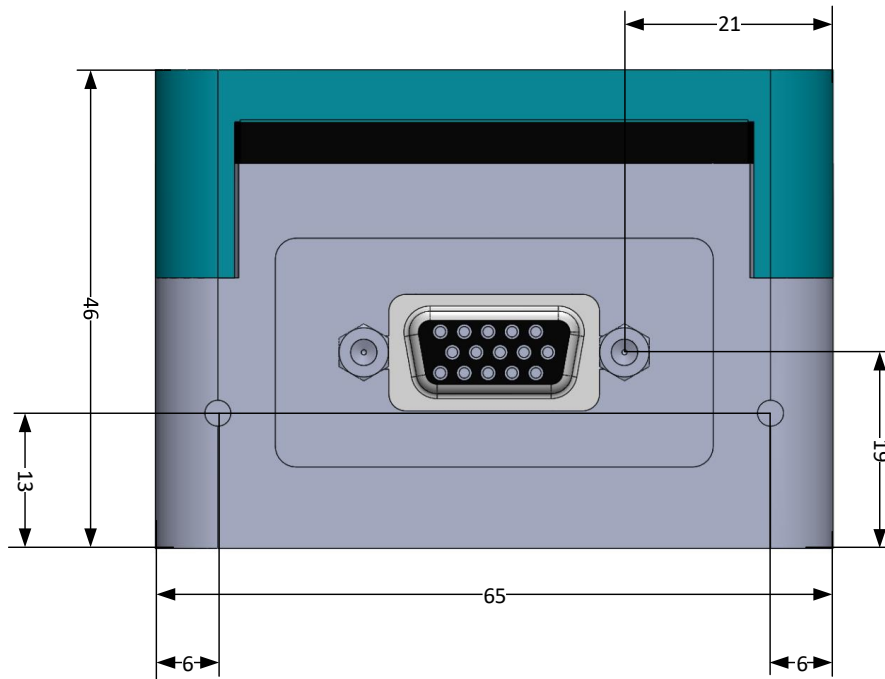


Figure 3-2: Front view without cover panel

### 3.1.3 Back view

Back view mounting hole size: M3

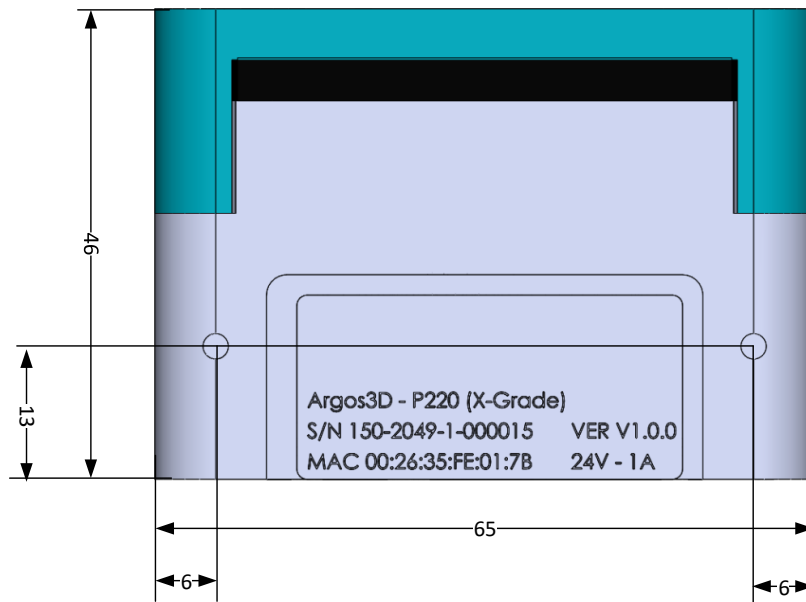


Figure 3-3: Back view without cover panel

### 3.1.4 Side view

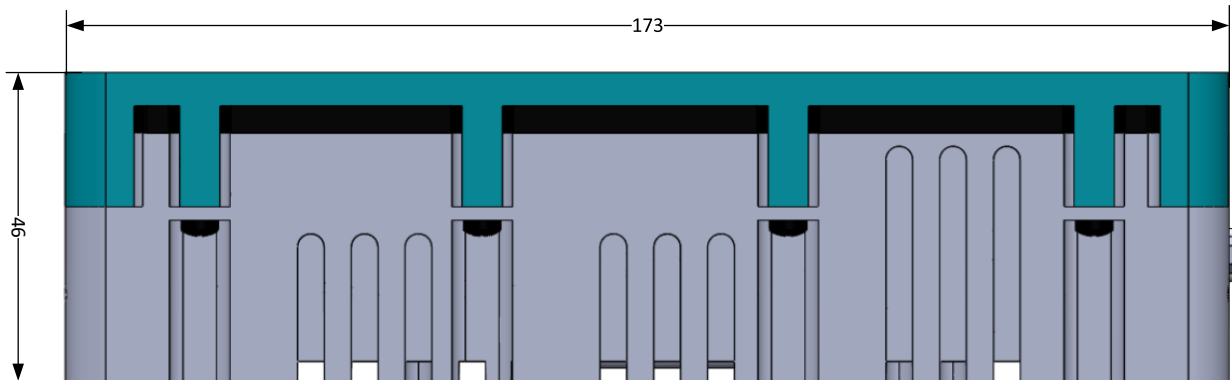


Figure 3-4: Side view without cover panel

### 3.1.5 Mount Spacing



#### Caution

Case may become hot!

The user is responsible to take care for an appropriate cooling.

To prevent the Argos3D-P230 from overheating, it is strongly recommended, to keep away nearby objects. This guarantees a constant airflow for proper cooling. This bounding box may be violated, when other cooling techniques are provided.

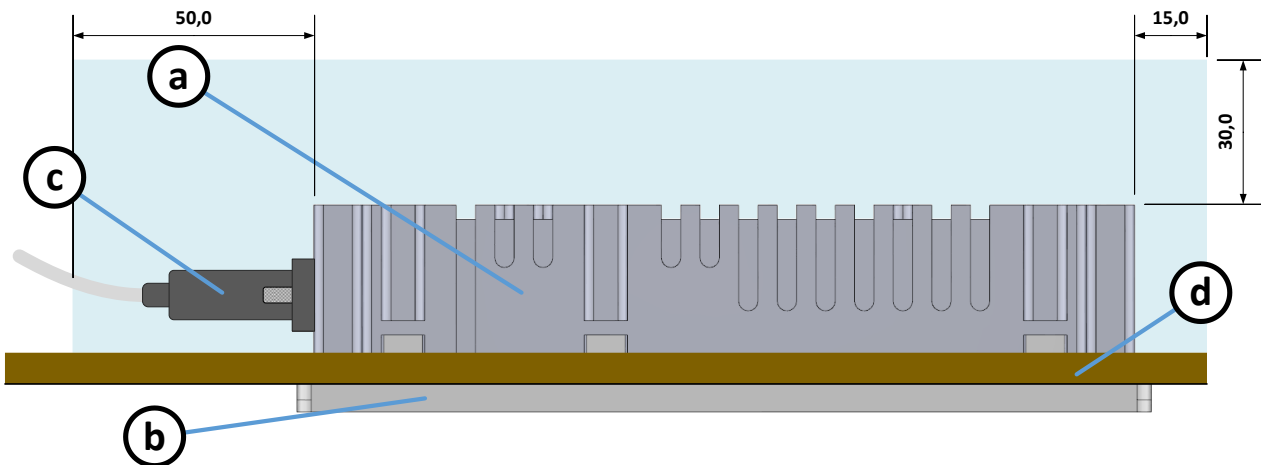


Figure 3-5: Bounding box

- a. Argos3D-P230 Case
- b. Argos3D-P230 Cover plate
- c. Mating IP67 connector
- d. Wall or mounting panel

## 4 Interface Description

### 4.1 Signal naming

Signal names are usually written in capital letters. They are noted in positive logic (positive asserted). If the signal is negative asserted an "n" will be added as prefix to the signal name.

#### Type:

The type describes the electrical characteristics of the signal. The following types are available:

- I Input
- O Output
- DN Negative Differential I/O
- DP Positive Differential I/O
- P Power supply
- 3.3V TTL TTL compatible signal with 3.3V high level and 0V low level.
- 50V tolerant Accepts input voltage levels up to 50V (2.5V high voltage threshold)

### 4.2 Connector Numbering

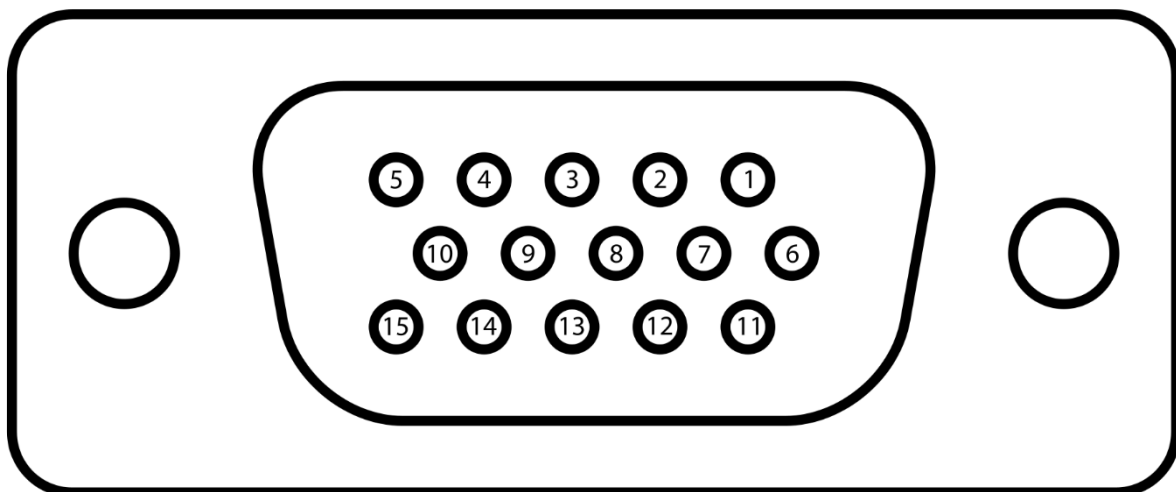


Figure 4-1: Connector Pin Numbering

## 4.2.1 Connector description

No.	Signal	Type	Description
1	ETH-B_N	DN	Ethernet Lane B
2	ETH-B_P	DP	Ethernet Lane B
3	GND	P	DIO Reference Ground
4	DIO	IO (50V tolerant)	Digital I/O Signal
5	V+	P	Positive Power Supply
6	ETH-C_N	DN	Ethernet Lane C
7	ETH-C_P	DP	Ethernet Lane C
8	ETH-D_N	DN	Ethernet Lane D
9	ETH-D_P	DP	Ethernet Lane D
10	nTRIGGER	IO (3V3 TTL)	Trigger Input
11	ETH-A_N	DN	Ethernet Lane A
12	ETH-A_P	DP	Ethernet Lane A
13	GND	P	DI Reference Ground
14	DI	I (50V tolerant)	Digital Input Signal
15	V-	P	Power Ground

Table 4-1: Connector Description

## 4.2.2 Power supply

The power supply pins are protected against wrong polarity.

Voltage range: 16V to 50V.



### Note

Use inherently limited power sources only!

## 4.2.3 DIO

The digital Input-Output interface has an optical isolated input and output stage. Driven by the GPIOs 1 (output) and GPIO 3 (input). See the Software User Manual specifications for GPIO functionality.

The output stage is a solid state relays, and gives the possibility to use the output as a simple switcher. The current is limited to 200mA.

If this interface is used as input, the corresponding output must be set to logically 0. Otherwise the input is constantly shorted. The maximum LOW input detection voltage is 2V, the minimum HIGH input detection voltage is 5V.

#### 4.2.4 Trigger In

The trigger Input is not optically isolated to minimize the propagation delay. But the input is protected against 50V clamp voltages. A standard 3.3V TTL signal should be used.

#### 4.2.5 RS485 Mounting Option

For some Applications a RS485 communication could be needed. Therefore, the internal hardware could be modified to route the RS485-A and –B signals to the connector in state of DI (RS485-A) and DIGND (RS485-B).

Ask BECOM Systems for custom modifications.

### 4.3 Mating Parts

The mating IP67 connector is an A-HDS15-HOOD-WP from ASSMANN WSW components GmbH and available for purchase e.g. at Digi-Key.

#### 4.3.1 Interconnection cable

#### 4.3.2 Development Adapter

For development purposes there is an adapter available with standard Ethernet RJ45 interface and a 2.1mm DC power supply socket.

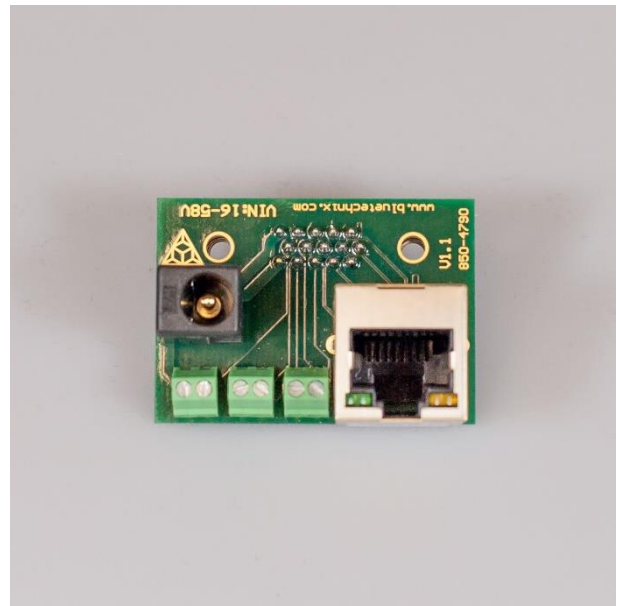
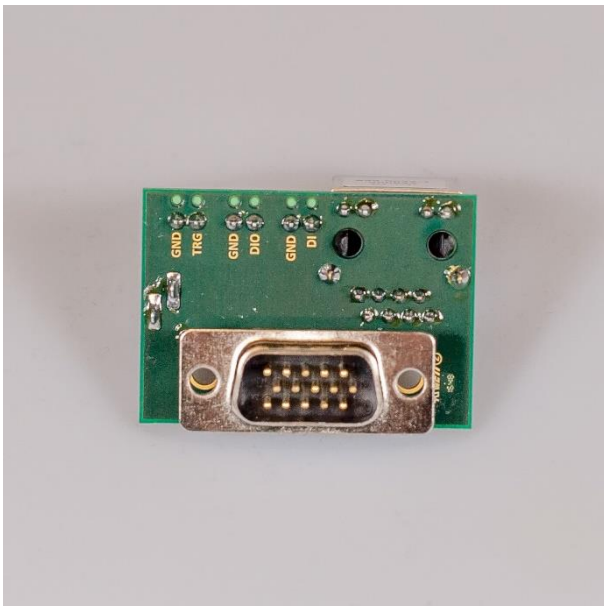


Figure 4-2: Adapter for Argos3D-P230

### 4.3.3 Interconnection Adapter

For interconnection there is an adapter available with standard Ethernet RJ45 interface and 2 pole headers for IO and power supply.

TBD

Figure 4-3: Interconnection adapter for Argos3D-P230

## **5 Software**

### **5.1 Firmware**

For a description of the firmware related interfaces, protocol descriptions, register settings, etc. please refer to the Software User Manual.

### **5.2 Demo Application**

For the first evaluation of the camera and to evaluate different settings and configurations a .NET demo application for Microsoft Windows is provided: BLT-ToF-Suite. The demo application can be downloaded from our support web site [support.bluetech-nix.com](http://support.bluetech-nix.com).

### **5.3 Getting Started Software Development Example**

To facilitate the integration of the Argos module in your own application a getting started example will be available on our download site. Please refer to our support site [support.bluetech-nix.com](http://support.bluetech-nix.com).



## 6 Appendix

### 6.1 Operating Conditions

Symbol	Parameter	Min	Typical	Max	Unit
$V_{IN}$	Input supply voltage <sup>3)</sup>	16	24	52	V
$I_{IN}$	Average Input current <sup>1)</sup>		TBD <sup>1)</sup>	TBD	A
$T$	Operating Temperature <sup>2)</sup>	-20		50 <sup>2)</sup>	°C
$T$	Storage Temperature	-40		+125	°C
<b>FITP<sup>4)</sup></b>	Frame-rate Integration Time Product			TBD	

Table 6-1: Operating Conditions



#### 1) Note

Valid for a frame-rate of 30fps and an integration time of 3500µs. The input current depends on the applied frame-rate and integration time.

#### 2) Note

The maximum operating temperature depends on the frame-rate and integration time.

#### 3) Note

The connector is used as section point.

#### 6.1.1 Input current

The average input current depends on the selected frame-rate (fps) and the integration time ( $t_{INT}$ ). The following figure shows typical values. The values on the x axis shows the FITP which has been calculated with the following equation:

$$FITP = t_{INT} [ms] \cdot fps \left[ \frac{1}{s} \right] \cdot 4$$

TBD

Figure 6-1: Input current @24V depending on frame-rate integration time product

#### 6.1.2 Temperature at the case

The following figure shows the expected case temperature @ 25°C ambient temperature depending on the frame-rate integration time product (FITP). The FITP has been calculated as follow:

$$FITP = t_{INT} [ms] \cdot fps \left[ \frac{1}{s} \right] \cdot 4$$

TBD

Figure 6-2: Expected cooling plate temperature depending on frame-rate integration time product

The temperature on the casing can be reduced by mounting an additional heat sink on the cooling plate.



**Caution**

The user is responsible to take care for an appropriate cooling if the Argos camera is mounted into a case.



**Caution**

Be careful to not stress the device beyond the limits, otherwise you may damage the device.

## 6.2 Optical Characteristics

Symbol	Parameter	Min	Typical	Max	Unit
#LEDs	Nr. of Laser diodes		8		
$\Lambda_{\text{CENTROID}}$	Centroid-Wavelength of Illumination		850		nm
$\Delta\lambda$	Spectral Bandwidth		5		nm
$I_e$	Radiant intensity		TBD		W/sr
FoV <sub>H</sub>	Horizontal Field of View		TBD		Deg
FoV <sub>V</sub>	Vertical Field of View		TBD		Deg

Table 6-2: Operating Parameters

## 6.3 Performance

### 6.3.1 Environmental Conditions

All the following measurements have been acquired at the following constant environmental conditions.

Parameter	Value
Temperature	23 °C
Humidity	35 %
Ambient light	500 Lux
Modulation Frequency	22,1 MHz
Frame-rate	30 fps

Table 6-3: Environmental Specification

### 6.3.2 Precision

The following graph shows the standard deviation over 100 samples.

TBD

Figure 6-3: Precision

### 6.3.3 Accuracy

The following figures has been determined by a frame-rate of 30fps and an integration time of 3,5ms with a reflectivity of 90%.

TBD

Figure 6-4: Accuracy

## 6.4 Sensor Location

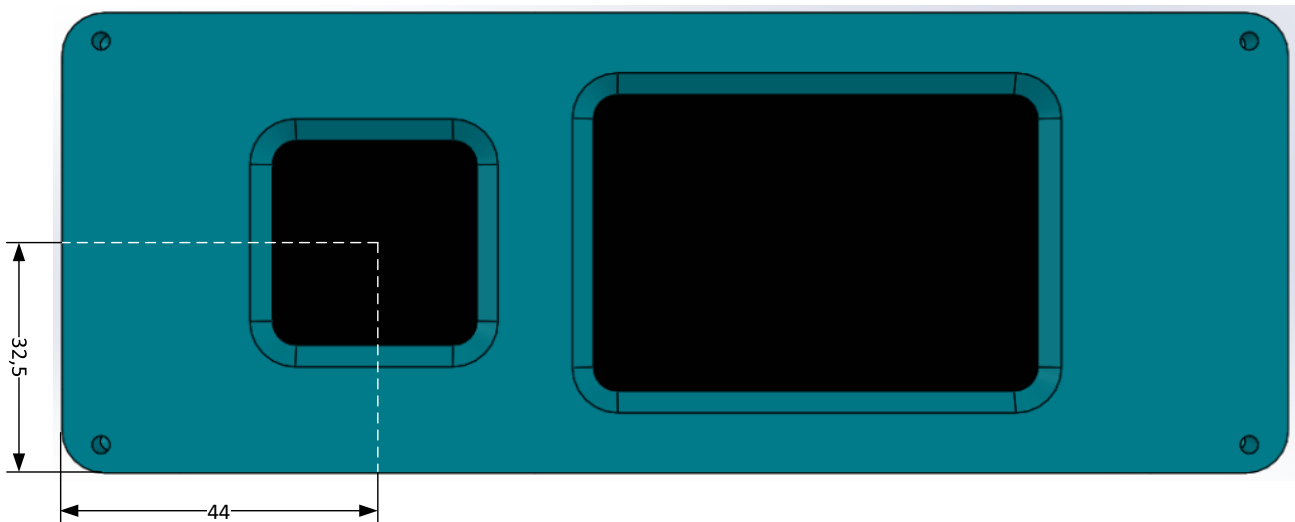


Figure 6-5: Location of optical center of sensor

## 7 Support

### 7.1.1 General Support

General support for products can be found at BECOM Systems' support site

#### Support Link

 <https://support.bluetechnix.com>

### 7.2 Related Products

- TIM-UP-IRS1125
- LIM-U-Laser-850-8

## 8 Product History

### 8.1 Version Information

#### 8.1.1 Argos3D-P230

Version	Type	Release date
V1.0.0	X-Grade	January 2019

Table 8-1: Overview Argos3D-P230 product changes



#### Note

Please refer to our support site for additional information about product changes.

### 8.2 Anomalies

Applies to	Date	Description
V1.0.0		- Modulation frequencies >40MHz are not working correctly. - Firmware update not working as intended. Workaround available.

Table 8-2 – Product anomalies

## 9 Document Revision History

Version	Date	Document Revision
1	11.01.2019	First preliminary of the document
2	30.01.2019	New Layout and typo corrected

Table 9-1: Revision history

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